

Negative Selection - A New Performance Measure for Automated Order Execution

Sanja Lončar* Miles Kumaresan † Nataša Krejić*

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Abstract

Measuring true slippage in algorithmic execution is a difficult task since the execution is a function of market activity. In this paper, we propose a performance measure for execution algorithms. The measure takes a posterior look at the trading window and allows us to determine what would have been the optimal order placement if we knew in advance the complete market information during the trading window. We define the performance measure as the difference between the optimal trading and the actual execution. This difference is calculated taking into account all process and traded quantities within the considered time window. Thus, we are capturing the impact caused by our own trading as a cost that affects all trades. Properties of Negative Selection, which make this measure well defined and objective are discussed. Some empirical results on real trade data is also presented.

Key words: performance measure, algorithmic trading, Arrival Price, VWAP

MSC: 90C90, 90B90.

1 Introduction

Automated Order Execution is the dominant way of executing orders at major stock markets. There is a variety of algorithms that are designed to serve different purposes and trader preferences. In Automated Order Execution a computer-based algorithm is used to buy (or sell) a position while attempting to achieve a benchmark specified by a client. Therefore the specified benchmark is used as a measure of execution performance. It is undoubtedly difficult to

*Department of Mathematics and Informatics, University of Novi Sad, Trg Dositeja Obradovića 4, 21000 Novi Sad, Serbia. Nataša Krejić is supported by Ministry of Education and Science, Republic of Serbia, Grant no. 174030, e-mail: sanja.lonchar@gmail.com, natasak@uns.ac.rs .

†Algonetix LLP, London, e-mail:miles.kumaresan@algonetix.com

define one standard measure for all order executions and all objectives as they can be very different and orders often come with many constraints. There are many types of benchmarks, some are established before the trading process, like Arrival Price, others are established during the trading process like VWAP, others quantify delays, or measure the performance with respect to the closing price etc.

The most important performance measures are VWAP (Volume Weighted Average Price) and Implementation shortfall (IS). Both measures are widely used in practice and represent the standard in the financial industry. Their properties are the subject of many academic studies and a number of algorithms are developed in order to minimize the slippage to VWAP and AP, [6, 8, 11, 13]. One of the problems with measuring slippage, whether it is VWAP or IS, is that they either distort the slippage measure or do not reflect the true nature of slippage. In the case of VWAP, by its own definition, this measure distorts slippage with increasing order size due to the impact caused by one's own orders. Although a good algorithm, the slippage measure is fundamentally flawed for large order size

In the case of the other equally dominant benchmark, IS, with Arrival Price as the reference price, although it is unbiased in terms of measuring slippage caused by price drift and market impact, it does not reflect the true slippage due to its reference to a static price (Arrival price). In other words, it does not capture the nature of absolute slippage. Consider the scenario where a buyer has to complete an order. Denote by t_0 the time when the buyer enters the market. If the price drifts up during the execution, the average execution price will be much higher than the reference price at t_0 . This slippage is naturally expected to the relatively high due to the difficult market conditions. If however the price drifted downwards by the same amount and the entire order quantity was on the best bid at t_0 and stayed there, the slippage would remain constant, representing the difference between the best bid price and Arrival Price. Although the slippage in the latter scenario is lower, the IS slippage measure relative to the fixed reference price does not reflect how much better we *could have done*. In an easy market condition like the case of falling price, intuitively, one may have expected to get negative slippage. However, the IS measure does not reflect this.

Hence the need for an absolute performance measure.

The performance measure which we propose in this paper aims at providing an alternative way of measuring the performance of execution algorithms. The measure takes a posteriori view of market conditions and its main characteristic is that it is completely objective. Roughly speaking, a posterior approach allows us to determine what would have been the optimal order placement if we knew in advance the complete market information during the trading window. Thus, we define the performance measure as the difference between the optimal trading position and the actual execution. This difference is calculated taking into account all traded quantities within the considered time window. This way, we are capturing the impact caused by our own trading as a cost that affects all trades, including our own and avoid the main problem with VWAP in the case of large trades.

Let us briefly explain the term Negative Selection. In execution, more specifically with regard to price movements, one does not want to get filled when the price comes one's way as the price may keep heading in that direction. In this case, it may be better to become more passive and hope to get a better price. Hence one's order being "selected" or "executed" is basically a sub-optimal execution. Negative Selection is an evolved term used to distinguish itself from the original concept in economics, namely adverse selection, referring to skewed and undesirable results due to asymmetry in information held by negotiating parties. In the case of a buyer and seller, asymmetric information in market direction will lead to the one with information edge benefitting from a transaction on the expense of the other.

Given a single buy order with a specified quantity Q and a time window $[0, T]$ for the execution, we define the optimal placement of the order as a solution of LP program. The unknowns of the LP are quantities at specific price levels, which add up to Q and would have yielded the lowest possible price during $[0, T]$, if we knew all market conditions during the trading window in advance. Thus the optimal placement is a vector calculated after the trade window $[0, T]$. The Negative Selection is defined as the distance between the actual trade, represented by the vector with a single nonzero component, and the optimal placement.

Any performance measure has to have several important properties. First of all, it should be able to distinguish clearly between filled and partially filled orders as well as between orders filled at different price levels. Furthermore, the performance measure needs to possess a continuity in the sense that a negligible change in the order size or in the fill price should yield negligible changes in the performance measure. Perhaps the most important property of a performance measure is that it should reflect the toughness of market condition at a particular time window and thus allow one to judge the quality of execution. We will show later on that the performance measure proposed in this paper possesses all of these qualities.

This paper is organized as follows. In Section 2 we define Negative Selection for a single (market or limit) order. All statements are given for the buy side to simplify the presentation and the sell side is completely symmetric. Then we define the Negative Selection of a complex order consisting of several positions - both passive and aggressive. Some empirical properties of Negative Selection are discussed in Section 3. We consider a black box trading strategy to measure the quality of different execution algorithms using Negative Selection. The results are compared with VWAP and IS as performance measures. Some conclusions are drawn in Section 4.

2 Negative Selection

The definition of Negative Selection is given here assuming that we have to buy Q shares either by placing a market order or taking a passive position at some of the bid levels. For the opposite case, selling Q shares, the definition is

completely symmetric. We consider a market governed by the limit order book implying that the orders are placed in queues by price and arrival time priority. Next, let us assume that the buy order of the size Q has to be executed within the time window $[0, T]$. At $t = 0$ the following information is available.

The **price vector**,

$$\mathcal{P} = [P_0, P_1, \dots, P_k]^T,$$

with P_0 being the price for market orders (i.e. the ask price at $t = 0$), and P_1, \dots, P_k being the bid prices at the corresponding bid levels. Clearly $P_k < P_{k-1} < \dots < P_1 < P_0$.

The **volume ahead**,

$$\mathcal{V} = [V_0, V_1, \dots, V_k]^T$$

represents the sizes of the existing orders in the corresponding bid queues at $t = 0$. We will assume that $V_0 = 0$, so a market order with price P_0 is immediately traded.

The **gain coefficients** are defined as

$$\mathcal{G} = [g_0, g_1, \dots, g_k]^T \text{ with } g_j = \frac{P_0 - P_j}{P_0}, j = 0, 1, \dots, k. \quad (1)$$

Clearly, $0 = g_0 < g_1 < \dots < g_k$.

We consider first a simple order of size Q , and it will be placed either as the market order or it will be placed passively, at some bid level at the end of the existing queue. We are assuming that Q is small enough so it can be traded as a simple order. Later on, we will discuss the case of larger Q , when one splits the quantity into several smaller orders to be executed within the trading window $[0, T]$. For technical reasons it is more convenient here to define the order vector

$$\mathcal{Q} = [Q_0, Q_1, \dots, Q_k]^T. \quad (2)$$

The order vector will have the following property

$$Q_m = Q \text{ for some } m \in \{0, 1, \dots, k\} \text{ and } Q_j = 0, j \neq m, j = 0, 1, \dots, k.$$

At the end of the trading window, $t = T$ some additional information are available.

The **traded quantity** during $(0, T]$ at every price level is represented by

$$\mathcal{T} = [T_0, T_1, \dots, T_k]^T$$

and we assume that $T_0 \geq Q$. i.e. there has been enough liquidity so the market order could have been filled at P_0 .

The **available quantity** now is defined as

$$\mathcal{A} = [A_0, A_1, \dots, A_k]^T, \quad A_j = \max\{T_j - V_j, 0\}.$$

The assumption $T_0 > Q$ implies that the set of indices $I_L = \{j : A_j > 0, j = 1, \dots, k\}$ is nonempty. So, the buy order Q could have been completely filled

during $[0, T]$. In other words, we are assuming that the order size Q is up to some percentage of the average traded volume within $[0, T]$. Denote further by $l = \max I_L$. We also define the set of indices

$$I_H = \{j : \sum_{i=j}^l A_i \geq Q, j = 0, 1, \dots, l\}.$$

This set is nonempty and let $h = \max I_H$ be its maximal element.

We are now in position to define the optimal placement. It is defined afterwards, i.e., at $t = T$ when all of the above vectors are available. The optimal placement represents the best we could have done at $t = 0$ to execute the order during $[0, T]$, if we knew in advance, at $t = 0$ all information for the trading time interval. In other words, the optimal placement represents the perfect scenario that would have allow us to execute the order with the lowest possible price. So, let us denote the optimal placement as

$$\mathcal{O} = [O_0, O_1, \dots, O_k]^T.$$

With this notation we are assuming that the quantity O_0 has been traded as a market order, O_1 has been placed at the first bid level and so on. Since the objective is to buy Q shares at the lowest possible price, the optimal placement is a solution of the following Linear Programming Problem.

$$\text{minimize } \sum_{i=0}^k P_i O_i \quad (3)$$

$$\text{subject to } \sum_{i=0}^k O_i = Q \quad (4)$$

$$\sum_{i=0}^j O_{k-i} \leq \sum_{i=0}^j A_{k-i}, j = 0, \dots, k-1 \quad (5)$$

$$O_j \geq 0, j = 0, \dots, k \quad (6)$$

Let us briefly explain the objective function and the constraints above. The objective function states that we want to minimize the total cost of buying $\sum_{i=1}^k O_i$ shares at prices levels P_0, \dots, P_l . The first constraint states that the quantity we want to buy is equal to Q . The second constraint specifies that we can buy only the available quantities at each price levels. But it is slightly more sophisticated than simply stating $O_i \leq A_i$ due to the price-queue priority execution of the market order book. The following toy example shows that filling the available quantities from below does not yield the smallest price for the total order of Q shares. Assume that order with $Q = 10$ is submitted at price 99.0 and we have ask1 and three available bid levels with the price vector

$$\mathcal{P} = [100, 99.5, 99.0, 98.5]^T.$$

Furthermore, let the queue in the order book at $t = 0$ (the volume ahead) be

$$\mathcal{V} = [0, 50, 10, 4]^T.$$

At $t = T$ the traded volume is

$$\mathcal{T} = [80, 50, 10, 9]^T,$$

so the available quantity is defined as

$$\mathcal{A} = [80, 0, 0, 5]^T.$$

If one considers the positions obtained by filling from below i.e. by taking the available quantities from the lowest price up until Q is reached, such order would be $[5, 0, 0, 5]^T$ and the price of buying 10 shares with such order would be $(5 \cdot 98.5 + 5 \cdot 100)/10 = 99.25$. On the other hand, solving the LP above one gets the optimal order as $\mathcal{O} = [1, 0, 9, 0]^T$ and its price is $(9 \cdot 99 + 1 \cdot 100)/10 = 99.1$. Hence the optimal placement i.e. the lowest price is not achieved by filling from below. This fact motivated the definition above and is a consequence of price-order trading mechanism.

The statement below claims that the LP (3)-(6) has a solution and its proof is given in Appendix.

Theorem 1. *The vector given by*

$$O_j = 0, j = 0, 1, \dots, h - 1 \quad (7)$$

$$O_h = Q - \sum_{j=h+1}^l A_j \quad (8)$$

$$O_j = A_j, j = h + 1, \dots, l \quad (9)$$

$$O_j = 0, j = l + 1, \dots, k, \quad (10)$$

is the unique solution of (3)-(6).

Proof is given in Appendix.

From now on we will refer to the vector (7)-(10) as the optimal placement. We are now ready to define the performance measure.

Definition 1. *For an order with the size Q at the price level P_m and execution time window $[0, T]$, Negative Selection is defined as*

$$\mathcal{N} = (\mathcal{O} - \mathcal{Q})^T \mathcal{G}, \quad (11)$$

where \mathcal{O} is the optimal placement vector, \mathcal{Q} is the order vector and \mathcal{G} is the vector of gain coefficients defined by (1).

The following properties of Negative Selection make it a well defined performance measure with desired qualities, objectivity and continuity.

Theorem 2. *The following properties hold:*

- a) *Negative Selection of an optimally placed order is zero.*
- b) *Negative Selection of a completely filled order is nonnegative.*
- c) *Negative Selection of a (partially) unfilled order is negative.*
- d) *Consider two orders with the same size Q placed at two price levels P_m and P_{m+1} with $P_m > P_{m+1}$. If \mathcal{N}_m and \mathcal{N}_{m+1} are their Negative Selections respectively, then $\mathcal{N}_m > \mathcal{N}_{m+1}$.*
- e) *Consider two different order of the sizes $Q_1 > Q_2$ placed at the same price level and denote their Negative Selections as \mathcal{N}_1 and \mathcal{N}_2 . Then*
 - 1) *If the larger order is filled then $\mathcal{N}_1 \geq \mathcal{N}_2$.*
 - 2) *If the larger order is unfilled then $\mathcal{N}_1 < \mathcal{N}_2$.*

Proof. See Appendix.

When placing a buy order, one is faced with the dilemma of being aggressive and cross the spread to buy at the prevailing asking price or take the chance of a better price by bidding at some bid price. In a rising market, a passive order at bid1 will remain unfilled which would lead to chasing the market to get filled, and yield a larger slippage than with crossing the spread. While in a sideways market, one is likely to save the spread cost by being passive. In the case of a falling market, a buyer is considered too aggressive if the entire order is placed at bid1 since one would achieve a better average price by having placed it at an even more passive price level. However, in the latter case, the probability of fill decreases significantly with more passive orders. Therefore, there is a need to split the orders into multiple price levels.

Let us now define Negative Selection for an order distributed across multiple price levels. Assume that the buy order for Q shares is allocated as the market order for Q_0 and a sequence of passive orders Q_1, \dots, Q_k at the corresponding bid levels $i = 1, \dots, k$. Clearly $Q_i \geq 0, i = 0, 1, \dots, k$ and $\sum_{i=1}^k Q_i = Q$. We can represent this multilevel order for buying Q shares as

$$\mathcal{S} = [Q_0, Q_1, \dots, Q_k]^T. \quad (12)$$

Each component of this vector \mathcal{S} has its own (simple) order vector as defined by (2) i.e.

$$\mathcal{Q}_i = [0, \dots, Q_i, \dots, 0]^T, i = 0, 1, \dots, k. \quad (13)$$

For each component of the vector in (13) we can calculate Negative Selection, \mathcal{N}_i as stated above. Then, Negative Selection for the complex orders is defined as

$$\mathcal{N}(\mathcal{S}) = [\mathcal{N}_0, \dots, \mathcal{N}_k]^T.$$

Unlike the case of simple order, here exists a certain interaction between the optimal placements for simple orders at different price levels i.e. one must take into account one's own trading.

3 Empirical Results

In this Section, we demonstrate some basic properties of Negative Selection (NS) using real trade data. The test data consists of tick data for Vodafone Group (VOD.L), AstraZeneca (AZN.L), Barclays PLC (BARC.L), and Sanofi SA (SASY.PA), during the period January - August 2006, all trading days, from 8:15 to 16:25.

One of the principal advantages of the NS as a performance measure is that it reflects the toughness of market at any given time. To demonstrate this property we compare the behaviour of NS, VWAP and IS benchmarks in both falling and rising markets. A simple example is considered. We place an order at bid1 until filled or the time of 10 minutes expires. If the order is not completely filled within 10 minutes, the residual is filled by crossing the spread at the end of given time window. We tested a sequence of orders with increasing sizes, from 0 to 35% of average traded quantity in the selected time window. The 10 minutes windows are chosen randomly. and the relevant trajectories for AZN are shown at Figure 1 and Figure 2. The price trajectories are shown at the left-hand side while the right-hand side shows the slippages with respect to all three benchmarks at both Figures. The horizontal axis shows the traded amount in thousands. The average traded quantity for AZN is 50000 shares in 10 minutes so the simulations are performed for orders of size 1 to 17500 shares with the step size of 500 shares.

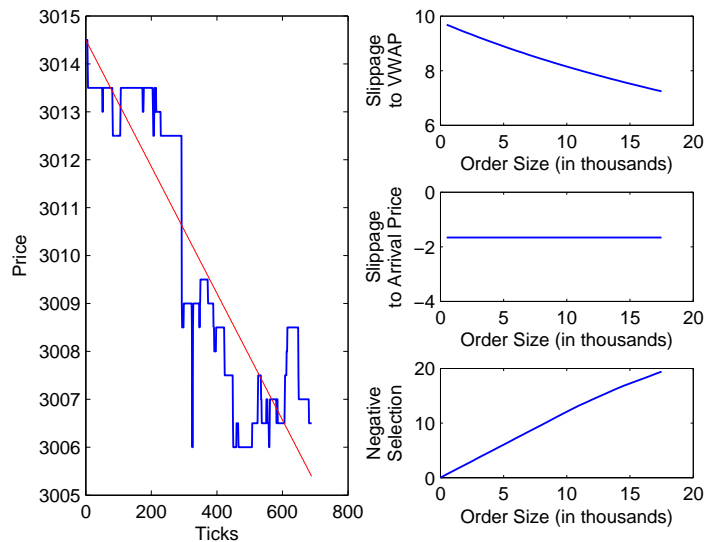


Figure 1: VWAP, Arrival Price and Negative Selection for falling market

Figure 1 shows the case of falling market. The slippage to VWAP is positive

and decreasing with the increase of order quantity. Being positive gives the true information of our execution, but the decrease with respect to traded quantity is actually a false information. The decreasing slippage implies that the execution strategy is good, although it is quite clear that in the falling market one should have placed orders at lower price levels. This decrease in the slippage is a consequence of the already mentioned VWAP flaw - the slippage is decreasing due to the impact of large traded quantity. With IS, the situation is different: the slippage is negative and constant. Its value is the difference of Arrival Price and bid1 price at the beginning of the time window. The negative sign of slippage here gives again a false information on the execution performance as a consequence of insensitivity of Arrival Price to the market conditions in the trading time window.

In the rising market shown in Figure 2, an order placed at bid1 can be regarded as passive. If the order is not filled, it will result in crossing the spread at the end of the time window and paying a higher price. The slippage to VWAP is positive because the order is filled at a price higher than the benchmark. But again, we see the decrease in the slippage with the increase of the order size, giving the false impression that the execution strategy is actually improving with the order size. The slippage to Arrival Price is high and positive. It is constant while there is enough liquidity at $t = T$, but when the order size increases enough - above the quantity available at ask1, the order starts to "walk the book" and the slippage to Arrival Price starts to rise. Whereas, NS is negative and increasing with the order size. Thus the information we get is correct - the execution strategy should have been more aggressive.

To demonstrate some properties of NS empirically, we consider a sequence of orders generated by a Black Box (BB) trading strategy with inventory. It is a momentum trading strategy generating signals using a mathematical model. The common parameters of a BB are time execution window, cancel threshold and order size. A combination of the time window width and the cancel threshold are used as the cancellation criterion: an order is canceled if either time expires or the cancellation threshold is reached. Therefore, there are only two possibilities: an order is (partially or completely) filled or canceled within the time window. The algorithm keeps track of open position i.e. all positions are closed with the opposite operation (buy/sell). For example, let us fix the order size to 100 shares. The first signal is to buy, and assume that 85 shares are bought until the cancel threshold is reached (or the execution time expires). The open position is now 85 shares. The second signal is sell and thus we want to sell $100 + 85 = 185$ shares, and so on. The BB parameters are selected as follows: the time window is $T = 10$ minutes and the cancel threshold is $45bps$. The tested order sizes vary from 1% and 5% of average traded volume in the time window, which is approximately 40,000 to 200,000 shares for Vodafone, 500 to 2,500 shares for AstraZeneca, 3,000 to 15,000 for Barclays PLC, 420 to 2,100 shares for Sanofi SA, respectively.

In addition to the Black Box trading strategy, we also consider the so-called Default strategy which is formulated as the alternation of buy and sell signal every 10 minute. When producing signals, it does not take into account the

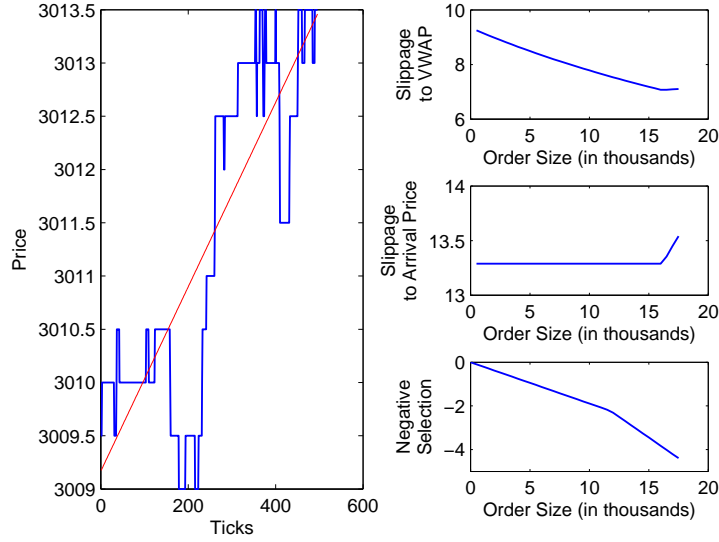


Figure 2: VWAP, Arrival Price and Negative Selection for rising market

actual market conditions. But like BB, it obeys rules regarding the possible cancellation of an order. As the quality of signals, in terms of profitability, is quite random, the purpose of Default strategy is to give us the baseline for market conditions during the observed period. The Default Strategy, in fact, reflects the toughness of the market as it landscapes the data.

The properties of Default and Black Box are presented in Table 1. The dollar sign represents monetary units i.e British Pound for Vodafone, AstraZeneca and Barclays PLC, and Euro for Sanofi SA and bid/ask1 denotes that buy order was placed at bid1, and sell order at ask1 price level. Analogously, we introduce notation bid/ask2 and bid/ask3. Clearly, the BB strategy has short-term alpha and can generate profit. The Default strategy is obviously losing money.

Ticker:		VOD		AZN		BARC		SASY	
		D	BB	D	BB	D	BB	D	BB
100% at bid/ask1	Total number of Triggers	8329	637	8219	1081	8337	1019	7505	438
	Total number of Trades	2969	536	4917	952	4395	657	4662	418
	Profitable days [%]	5.36	64.49	3.61	59.35	2.38	57.67	8.19	51.24
	Profit [in 000]	-68,230	12,942	-18,628	2,483	-29,055	1,996	-384	33
	Slippage to VWAP [bps]	1.84	-7.36	1.84	-2.33	2.27	-0.75	2.14	-3.58
	Win[\$]/Loss[\$]	-0.35	1.55	-0.39	1.31	-0.35	1.23	-0.46	1.31
	Average Profit per Trade[\$]	-22,981	24,145	-3,788	2,608	-6,611	3,038	-82	80
	Profitable trades [%]	25.73	54.10	35.69	52.84	32.63	52.97	34.92	53.59
	Total number of Triggers	8329	637	8219	1081	8337	1019	7505	438
100% at bid/ask2	Total number of Trades	475	91	3100	714	2066	326	2629	357
	Profitable days [%]	31.21	51.11	12.65	59.15	16.67	64.44	19.88	59.13
	Profit [in 000]	-15,183	536	-11,856	2,589	-12,404	1,903	-191	70
	Slippage to VWAP [bps]	0.78	-0.48	1.25	-2.8	1.12	-0.92	1.3	-7.23
	Win[\$]/Loss[\$]	-0.39	1.08	-0.43	1.45	-0.46	1.48	-0.55	1.95
	Average Profit per Trade [\$]	-31,965	5,896	-3,824	3,626	-6,004	5,838	-73	196
	Profitable trades [%]	33.89	46.15	40.52	56.72	38.67	59.2	42.91	60.22
	Total number of Triggers	8329	637	8219	1081	8337	1019	7505	438
	100% at bid/ask3	Total number of Trades	137	31	1935	454	1002	153	1506
Profitable days [%]		36.99	50	25.3	59.68	30.12	68.48	36.84	67.44
Profit [in 000]		-3,159	-286	-7,447	1,361	-5,857	1,087	-81	43
Slippage to VWAP [bps]		0.49	-0.12	0.85	-2.07	0.54	-0.62	0.71	-4.31
Win[\$]/Loss[\$]		-0.58	-0.9	-0.46	1.34	-0.5	1.52	-0.69	1.9
Average Profit per Trade [\$]		-23,056	-9,215	-3,848	2,998	-5,845	7,103	-54	196
Profitable trades [%]		44.53	48.39	43.36	57.49	40.92	67.32	46.88	60.18

Table 1: Properties of Default (D) and Black Box (BB) trading strategy for order size of 5% of average traded volume in the time window

Ticker:			VOD	AZN	BARC	SASY
Mean Negative Selection for orders of 1% and 5% of AVQ	bid/ask1	1%	5.73	0.36	0.52	0.55
		5%	17.00	1.53	1.02	2.47
	bid/ask2	1%	-79.98	0.13	-1.90	0.26
		5%	-409.92	0.40	-11.12	1.03
	bid/ask3	1%	-164.15	-0.13	-4.49	-0.05
		5%	-831.74	-0.88	-24.11	-0.51
	bid/ask4	1%	-248.26	-0.43	-7.20	-0.36
		5%	-1251.97	-2.36	-37.61	-2.01
	bid/ask5	1%	-332.61	-0.78	-10.02	-0.69
		5%	-1673.73	-4.13	-51.76	-3.66

Table 2: Negative Selection for price levels bid/ask1-bid/ask5

Table 2 contains the simulation results for the BB strategy. We tested two order sizes and five order placement positions, for all four stocks, across the whole data set. The order sizes were 1% and 5% of average traded quantity in 10 minutes intervals. The placement positions include all five bid/ask positions. In other words, for a buy signal we considered placing the order at bid1, bid2,...,bid5 and analogously for a sell signal. The mean values across the whole data set are given in Table 2. One can easily see that the theoretical properties stated in Theorem 2 are empirically confirmed. For all stocks, Negative Selection of the smaller order (1%) is smaller than the Negative Selection of the larger order (5%). Furthermore, as the trading becomes more passive the Negative Selection is becoming more negative. The actual mean values of negative selection vary quite significantly between four considered stocks. In other words, Negative Selection indeed captures the true properties of the market. VOD is the most liquid stock with the widest spread ($21.65bps$) in this data sample - trading takes place at bid1 and ask1 for an extended period followed by a shift in price to the next price level or a few price levels above / below and repeat the bid/ask bouncing. Unlike VOD, AZN is the least liquid stock with the smallest spread ($6.42bps$). AZN price tends to trade in a narrow price channel e.g. going from bid1 to bid3 and then bounce back and repeated the process, with a different price trajectory. Such behaviour justifies the fact that VOD has the best performance, in terms of profits and NS, at bid/ask1 and for AZN we see the same at level bid/ask2.

More detailed results for the first three bid/ask levels are given in Table 3. Again, the results are in line with theoretical properties. We also included mean values of T_{fill} and T_{cancel} . T_{fill} is the exact time it took to fill, while T_{cancel} denotes the time after which a (partially) unfilled order has been canceled. Remember that cancellation is due either to the expiration of the execution time (in that case $T_{cancel} = 10$ minutes) or to the price movement i.e. reaching the price threshold (so $T_{cancel} < 10$ minutes).

Ticker:		VOD	AZN	BARC	SASY
bid/ask1	Mean (NS)	25.23	2.38	0.48	3.82
	St.Dev. (NS)	605.60	4.76	25.00	5.13
	Coeff. Of Vari- ation (NS)	24.00	2.00	52.48	1.34
	Mean/St.Dev (NS)	0.04	0.5	0.02	0.74
	Median (NS)	0.00	1.12	0.00	2.61
	Mean(T_{fill})	4.37	3.86	4.33	3.36
	Mean(T_{cancel})	9.03	9.20	9.59	7.57
	bid/ask2	Mean (NS)	-450.57	0.49	-14.14
St.Dev. (NS)		428.19	4.21	22.90	4.36
Coeff. Of Vari- ation (NS)		-0.95	8.63	-1.62	3.28
Mean/St.Dev (NS)		-1.05	0.12	-0.62	0.3
Median (NS)		-428.27	0.00	-14.40	0.00
Mean(T_{fill})		5.99	4.76	5.33	4.48
Mean(T_{cancel})		9.56	9.49	9.71	9.00
bid/ask3		Mean (NS)	-863.71	-1.16	-26.60
	St.Dev. (NS)	406.38	4.09	21.21	3.95
	Coeff. Of Vari- ation (NS)	-0.47	-3.52	-0.80	-4.78
	Mean/St.Dev (NS)	-2.13	-0.28	-1.25	-0.21
	Median (NS)	-847.46	-1.52	-25.86	-1.38
	Mean(T_{fill})	5.62	5.36	5.62	5.17
	Mean(T_{cancel})	9.56	9.54	9.65	9.37

Table 3: Negative Selection statistics and Fill/Cancel average time for Black Box (BB) trading strategy

Figure 3 illustrates the property of NS described in Theorem 2 d) for VOD. A random sample of triggers is used. Orders of 5% of the average traded quantity are placed at bid/ask1, bid/ask2, ..., bid/ask5. Similar results are obtained for the other shares, AZN, BARC, and SASY. Clearly, the Negative Selection behaves as stated in Theorem 2 d). It is becoming more negative as the order placement is more passive.

When an order is filled we notice that passive orders have absolute NS lower than aggressive, because the price went in our direction affecting optimal placement to be passive. This way passive orders were "awarded" by the smaller value of NS, i.e. they were closer to optimal placement. In the opposite case, when for example for all bid levels the order was unfilled, for each level NS is negative, but the bid1 order has the lowest absolute value. This reflects the fact that the price went in the adverse direction, so the best strategy was to trade aggressively i.e. more passive orders were undesirable.

Figure 4 illustrates Theorem 2 e). We are interested in NS for the orders at the same price level but of different size. Again, we consider two order sizes, 1% and 5% of the average traded quantity. Clearly, if there was enough liquidity to fill the larger order, then there was enough liquidity to fill the smaller one. In

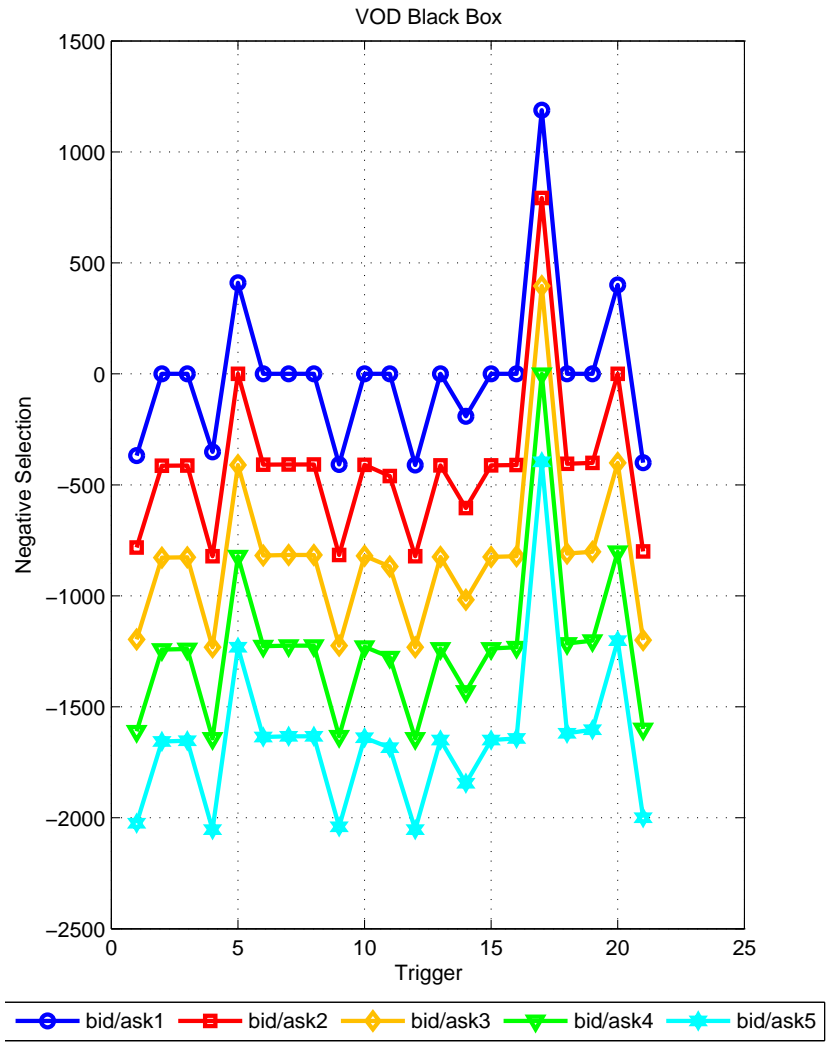


Figure 3: Comparison of Negative Selection for VOD by price levels

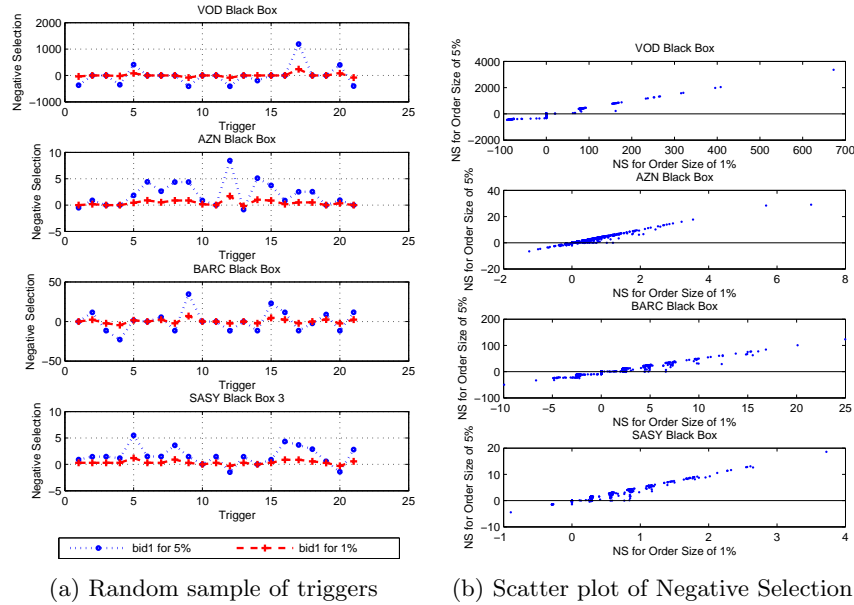


Figure 4: Comparison of Negative Selection by order size for bid/ask1

this case, NS of larger order dominates the NS of the smaller order, which enable us to capture the impact caused by our own trading. It also indicates that in the situation when the price is going in our direction, both orders will be filled at an unfavourable price, but the effect is larger for the large order, i.e., the overall costs are larger for suboptimal large order than the cost of a suboptimal smaller order. On the other hand, if the larger order is unfilled, there are two possibilities: First, the smaller order is filled i.e. there was enough liquidity to fill the smaller one, but not enough to fill the larger. Hence, the smaller order has nonnegative NS, while the large order has negative NS. In the second case, the smaller order is also unfilled. Then, both orders have negative NS, with the larger order being more negative. Obviously, the strategy was too passive for the smaller order, but for the larger order, there is an additional cost for passive behaviour, as filling the larger order, when the price is going away from us, requires more aggressive behaviour.

Figure 5 represents the relative distribution of Negative Selection for bid/ask1 for BB. For more liquid stocks, Vodafone and Barclays, BB strategy has positive Negative Selection for bid/ask1, and negative for bid/ask2. This indicates that price was trending in an adverse direction so the aggressive strategy was more profitable. Moreover, trading at bid/ask2 and especially at bid/ask3 level, because of passive behaviour we were exposed to the cost of crossing the spread. For less liquid stocks AstraZeneca and Sanofi trading at bid/ask1 resulted in positive Negative Selection, which means that with aggressive trading, a majority of orders were filled at the unfavourable price, while at bid/ask2 BB has

slightly positive Negative Selection that implies that it was more profitable. At bid/ask3 we see that the strategy is too passive resulting in less profit.

The distribution of Cancel Time and Fill time for the same sequence of orders is depicted on Figure 6. Cancel Time corresponds to points with negative Negative Selection, while Fill time is on the nonnegative side of the axis. Basically, this is a consequence of Theorem 2a)-c), because filled orders have nonnegative NS, while unfilled orders have negative NS. Time limit for all orders was $T = 10$ minutes causing a grouping of cancel time data at the 10th minute.

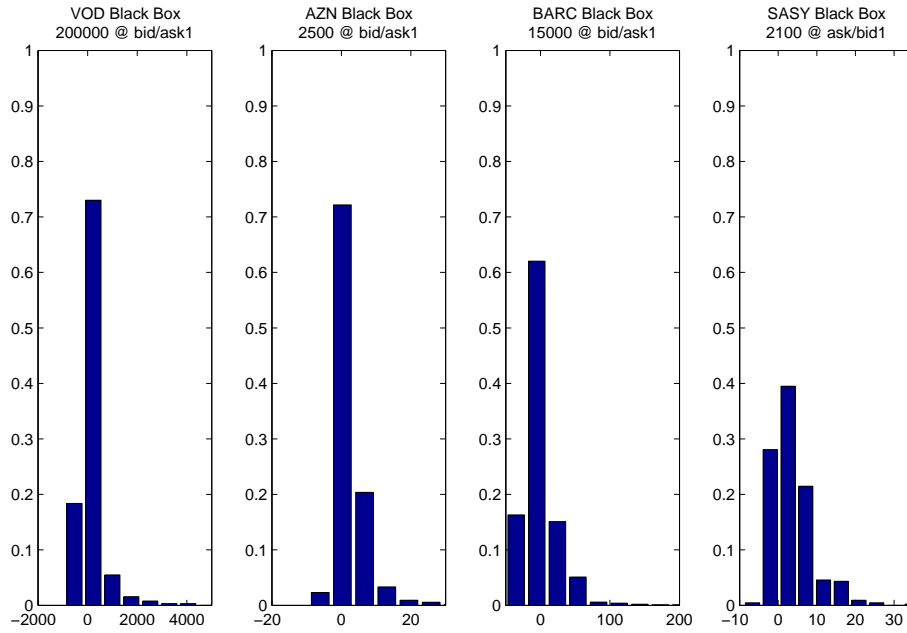


Figure 5: Retaliative frequency histogram of Negative Selection

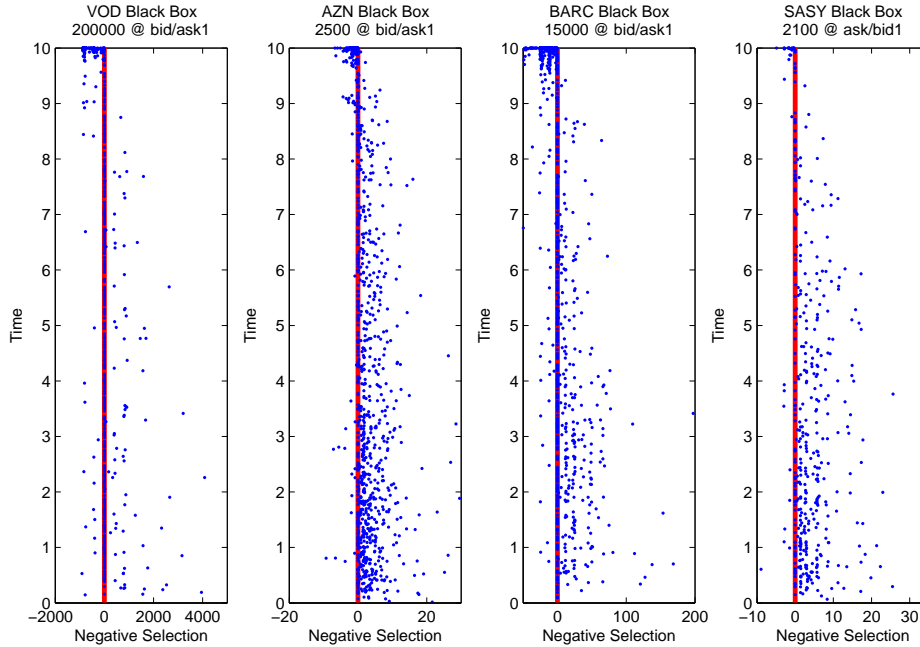


Figure 6: The distribution of Cancel Time and Fill time

4 Conclusion

We presented Negative Selection as a post-trade performance measure for execution algorithms. It is based on the concept of Optimal Placement - the placement at $t = 0$ that would provide the most favourable execution price in time window $[0, T]$ if all market information had been available. Thus, it is a posteriori measure. Negative Selection possesses theoretically desirable properties - it is continuous, captures the toughness of market and price impact and thus it is completely objective.

Properties of Negative Selection are tested using simulator built in Matlab and MySQL, on real trade data for three liquid stocks from London Stock Exchange and one stock from Euronext. The obtained empirical results are aligned with the theoretical expectations and demonstrate the ability of Negative Selection to capture all important properties of a trading strategy. The comparison between NS and two main benchmarks, VWAP and IS are also presented.

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Appendix

Consider the following linear programming problem,

$$\begin{aligned} & \text{minimize } J(x) = c^T x \\ & \text{subject to } Ax = b \\ & \quad \quad \quad Cx \geq d \end{aligned} \tag{14}$$

where $A \in \mathbb{R}^{m \times n}$, $C \in \mathbb{R}^{p \times n}$, $x, c \in \mathbb{R}^n$, $b \in \mathbb{R}^m$, $d \in \mathbb{R}^p$.

Theorem. [17] *A solution x^* of linear programming problem (14) is unique if and only if it remains a solution to all linear programs obtained from (14) by arbitrary but sufficiently small perturbation of its cost vector c , or equivalently for each $q \in \mathbb{R}^n$ there exist a positive real number ϵ such that x^* remains a solution of the perturbed linear program*

$$\begin{aligned} & \text{minimize } J(x) = (c + \epsilon q)^T x \\ & \text{subject to } Ax = b \\ & \quad \quad \quad Cx \geq d \end{aligned} \tag{15}$$

Proof of Theorem 1

Proof. Given that $A_j = 0$ for $j = l + 1, \dots, k$, constrains (5)-(6) imply $O_j = 0$ for $j = l + 1, \dots, k$. Thus (10) holds. So, it is sufficient to consider the following problem

$$\min_{O_0, \dots, O_l} \sum_{i=0}^l P_i O_i \tag{16}$$

$$\sum_{i=0}^l O_i = Q \tag{17}$$

$$\sum_{i=0}^j O_{l-i} \leq \sum_{i=0}^j A_{l-i}, j = 0, \dots, l-1 \tag{18}$$

$$O_j \geq 0, j = 0, \dots, l \tag{19}$$

The standard form of (16)-(19) is the following

$$\begin{aligned} & \min J(x) = c^T x \\ & \quad \quad \quad Mx = b \\ & \quad \quad \quad x \geq 0 \end{aligned} \tag{20}$$

where $c = [c_0, \dots, c_{2l}]^T$, $x = [x_0, \dots, x_{2l}]^T$ and $b = [b_0, \dots, b_l]^T$ are defined by

$$c_j = \begin{cases} P_j, & j = 0, \dots, l \\ 0, & j = l + 1, \dots, 2l \end{cases}$$

$$x_j = \begin{cases} O_j, & j = 0, \dots, l \\ d_{j-l}, & j = l+1, \dots, 2l \end{cases}$$

$$b_j = \begin{cases} Q, & j = 0 \\ \sum_{i=j}^l A_i, & j = 1, \dots, l \end{cases}$$

and

$$M = \left[\begin{array}{cccccccc|cccccccc} 1 & 1 & \dots & 1 & 1 & 1 & \dots & 1 & 1 & 0 & \dots & 0 & 0 & 0 & \dots & 0 & 0 \\ 0 & 1 & \dots & 1 & 1 & 1 & \dots & 1 & 1 & 1 & \dots & 0 & 0 & 0 & \dots & 0 & 0 \\ \vdots & \vdots & \ddots & \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & \dots & 1 & 1 & 1 & \dots & 1 & 1 & 0 & \dots & 1 & 0 & 0 & \dots & 0 & 0 \\ 0 & 0 & \dots & 0 & 1 & 1 & \dots & 1 & 1 & 0 & \dots & 0 & 1 & 0 & \dots & 0 & 0 \\ 0 & 0 & \dots & 0 & 0 & 1 & \dots & 1 & 1 & 0 & \dots & 0 & 0 & 1 & \dots & 0 & 0 \\ \vdots & \vdots & \ddots & \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & \dots & 0 & 0 & 0 & \dots & 1 & 1 & 0 & \dots & 0 & 0 & 0 & \dots & 1 & 0 \\ 0 & 0 & \dots & 0 & 0 & 0 & \dots & 0 & 1 & 0 & \dots & 0 & 0 & 0 & \dots & 0 & 1 \end{array} \right]$$

The following vector is a basic solution of problem (20)

$$v = [0, 0, \dots, 0, Q - \sum_{j=h+1}^l A_j, A_{h+1}, \dots, A_{l-1}, A_l, (\sum_{j=1}^l A_j) - Q, \dots, (\sum_{j=h-1}^l A_j) - Q, (\sum_{j=h}^l A_j) - Q, 0, \dots, 0, 0]^T, \quad (21)$$

with the basis matrix B and the non-basis matrix N

$$B = \left[\begin{array}{c|c|c} 1 & \mathbf{1}_{1 \times (l-h)} & \mathbf{0}_{1 \times h} \\ \hline \mathbf{1}_{h \times 1} & \mathbf{1}_{h \times (l-h)} & E_{h \times h} \\ \hline \mathbf{0}_{(l-h) \times 1} & U(1)_{(l-h) \times (l-h)} & \mathbf{0}_{(l-h) \times h} \end{array} \right]$$

$$N = \left[\begin{array}{c|c} U(1)_{h \times h} & \mathbf{0}_{h \times (l-h)} \\ \hline \mathbf{0}_{1 \times h} & \mathbf{0}_{1 \times (l-h)} \\ \hline \mathbf{0}_{(l-h) \times h} & E_{(l-h) \times (l-h)} \end{array} \right].$$

Here, $U(c)$ is an upper triangular matrix with all nonzero elements equal to c , $L(c)$ is a lower triangular matrix with all nonzero elements equal to c , $\mathbf{0}$ is the zero matrix, and $\mathbf{1}$ has elements equal to 1, E is the identity matrix. As the inverse of B is

$$B^{-1} = \left[\begin{array}{c|c|c} 1 & \mathbf{0}_{1 \times h} & [-1, \mathbf{0}_{1 \times (l-h-1)}] \\ \hline \mathbf{0}_{(l-h) \times 1} & \mathbf{0}_{(l-h) \times h} & U(1)_{(l-h) \times (l-h)}^{-1} \\ \hline -\mathbf{1}_{h \times 1} & E_{h \times h} & \mathbf{0}_{h \times (l-h)} \end{array} \right],$$

and

$$B^{-1}N = \left[\begin{array}{c|c} \mathbf{1}_{1 \times h} & [-1, \mathbf{0}_{1 \times (l-h-1)}] \\ \hline \mathbf{0}_{(l-h) \times h} & U(1)_{(l-h) \times (l-h)}^{-1} \\ \hline L(-1)_{h \times h} & \mathbf{0}_{h \times (l-h)} \end{array} \right],$$

the Simplex table for the basic solution v is

	O_0	O_1	\dots	O_{h-1}	d_{h+1}	d_{h+2}	\dots	d_l	v_B
O_h	1	1	\dots	1	-1	0	\dots	0	$Q - \sum_{j=h+1}^l A_j$
O_{h+1}	0	0	\dots	0	1	-1	\dots	0	A_{h+1}
O_{h+2}	0	0	\dots	0	0	1	\dots	0	A_{h+2}
\vdots	\vdots	\vdots	\dots	\vdots	\vdots	\vdots	\dots	\vdots	\vdots
O_{l-1}	0	0	\dots	0	0	0	\dots	-1	A_{l-1}
O_l	0	0	\dots	0	0	0	\dots	1	A_l
d_1	-1	0	\dots	0	0	0	\dots	0	$(\sum_{j=1}^l A_j) - Q$
d_2	-1	-1	\dots	0	0	0	\dots	0	$(\sum_{j=2}^l A_j) - Q$
\vdots	\vdots	\vdots	\dots	\vdots	\vdots	\vdots	\dots	\vdots	\vdots
d_h	-1	-1	\dots	-1	0	0	\dots	0	$(\sum_{j=h}^l A_j) - Q$
	Δ_{O_0}	Δ_{O_1}	\dots	$\Delta_{O_{h-1}}$	$\Delta_{d_{h+1}}$	$\Delta_{d_{h+2}}$	\dots	Δ_{d_l}	

All reduced costs are negative: $\Delta_{O_j} = P_h - P_j < 0$, $j = 0, \dots, h-1$ and $\Delta_{d_j} = P_j - P_{j-1} < 0$, $j = h+1, \dots, l$. The basic solution v is an optimal solution of problem (20). Further, the vector

$$[0, 0, \dots, 0, Q - \sum_{h+1}^l A_j, A_{h+1}, \dots, A_{l-1}, A_l]^T$$

is an optimal solution of (16)-(19) and the optimal solution of (3)-(6) is indeed given by (7)-(10).

The uniqueness will be proved using Mangasarian's result [17], Theorem 1 above.

Let $q \in \mathbb{R}^{l+h+1}$ be an arbitrary vector, we will show that there is positive number $\epsilon > 0$ such that the vector v , defined in (21), remains a solution of perturbed problem

$$\begin{aligned} & \text{minimize } J(x) = (c + \epsilon q)^T x \\ & \text{subject to } Mx = b \\ & \quad x \geq 0. \end{aligned} \tag{22}$$

The vector v is a basic solution of the problem (22), and the reduced costs for (22) are

$$\begin{aligned}\Delta_{O_j} &= P_h + \epsilon q_h - (P_j + \epsilon q_j) = P_h - P_j + \epsilon(q_h - q_j), \quad j = 0, \dots, h-1 \\ \Delta_{d_j} &= (P_j + \epsilon q_j) - (P_{j-1} + \epsilon q_{j-1}) = (P_j - P_{j-1}) + \epsilon(q_j - q_{j-1}), \quad j = h+1, \dots, l.\end{aligned}$$

By choosing ϵ as

$$\epsilon = \min(\{\frac{P_j - P_h}{2(q_h - q_j)} | q_h > q_j, j = 0, \dots, h-1\} \cup \{\frac{P_{j-1} - P_j}{2(q_j - q_{j-1})} | q_j > q_{j-1}, j = h+1, \dots, l\}),$$

we get

$$\begin{aligned}\Delta_{O_j} &< \frac{1}{2}(P_h - P_j) < 0, \quad j = 0, \dots, h-1 \\ \Delta_{d_j} &< \frac{1}{2}(P_j - P_{j-1}) < 0, \quad j = h+1, \dots, l.\end{aligned}$$

This means that v is an optimal solution of (22). \square

Proof of Theorem 2

a) If the order is optimally placed then $\mathcal{O} = \mathcal{Q}$, so

$$\mathcal{N} = (\mathcal{O} - \mathcal{Q})^T \mathcal{G} = (\mathcal{O} - \mathcal{O})^T \mathcal{G} = 0$$

b) If the order is filled at level m then $m \in I_H$ and $m \leq h$ holds. Furthermore,

$$\begin{aligned}\mathcal{N} &= (\mathcal{O} - \mathcal{Q})^T \mathcal{G} = \sum_{i=0}^k O_i g_i - Q g_m \geq \sum_{i=0}^k O_i g_h - Q g_m \\ &= Q g_h - Q g_m = Q(g_h - g_m) \geq 0\end{aligned}$$

c) If the order is unfilled at level m then $m \geq l$. Assume that $m < l$. Then $P_m > P_l$ and as $A_l > 0$, it is clear that there has been some trading at the level l . Therefore, the price decreased from P_m to P_l . But that further implies that all orders at the price P_m were filled, which is in contradiction with the assumption $m < l$. Thus,

$$\begin{aligned}\mathcal{N} &= (\mathcal{O} - \mathcal{Q})^T \mathcal{G} = \sum_{i=0}^k O_i g_i - Q g_m < \sum_{i=0}^k O_i g_l - Q g_m \\ &= Q g_l - Q g_m = Q(g_l - g_m) \leq 0.\end{aligned}$$

d)

In this case we have

$$\begin{aligned}\mathcal{N}_m - \mathcal{N}_{m+1} &= (\mathcal{O} - \mathcal{Q}_m)^T \mathcal{G} - (\mathcal{O} - \mathcal{Q}_{m+1})^T \mathcal{G} = (\mathcal{Q}_{m+1} - \mathcal{Q}_m)^T \mathcal{G} \\ &= Q g_{m+1} - Q g_m = Q(g_{m+1} - g_m) > 0.\end{aligned}$$

e) Let P_l be the lowest price level for which $A_l > 0$. For $Q_1 > Q_2$ we have

$$I_{H_1} = \{j \mid \sum_{i=j}^l A_i \geq Q_1, j = 0, \dots, l\},$$

$$I_{H_2} = \{j \mid \sum_{i=j}^l A_i \geq Q_2, j = 0, \dots, l\},$$

$$h_1 = \max(I_{H_1}),$$

and

$$h_2 = \max(I_{H_2}).$$

It is quite clear that $h_2 \geq h_1$. The optimal placements are given by $\mathcal{O}_{Q_1} = [O_0^1, \dots, O_k^1]^T$ and $\mathcal{O}_{Q_2} = [O_0^2, \dots, O_k^2]^T$. The order sizes could be rewritten as

$Q_1 = \sum_{i=h_1}^l O_i^1$ and $Q_2 = \sum_{i=h_2}^l O_i^2$. The definition of optimal placement implies $O_i^1 = O_i^2, i = h_2 + 1, \dots, l$, and

$$\begin{aligned} Q_1 - Q_2 &= \sum_{i=h_1}^l O_i^1 - \sum_{i=h_2}^l O_i^2 \\ &= \sum_{i=h_1}^{h_2-1} O_i^1 + O_{h_2}^1 + \sum_{i=h_2+1}^l O_i^1 - \sum_{i=h_2+1}^l O_i^2 - O_{h_2}^2 \\ &= \sum_{i=h_1}^{h_2-1} O_i^1 + O_{h_2}^1 - O_{h_2}^2 \end{aligned}$$

1. If both orders are filled then $m \leq h_1 \leq h_2 \leq l$. Let us consider the following two cases.

(a) If $A_l \geq Q_1$ and $m = l$, then $m = h_1 = h_2 = l$,

$$\mathcal{N}_1 - \mathcal{N}_2 = (\mathcal{O}_{Q_1} - \mathcal{Q}_1)^T \mathcal{G} - (\mathcal{O}_{Q_2} - \mathcal{Q}_2)^T \mathcal{G} = (Q_1 - Q_1)g_m - (Q_2 - Q_2)g_m = 0.$$

(b) If $A_l < Q_1$ then $m \leq h_1 < h_2 = l$ or $m \leq h_1 \leq h_2 < l$,

$$\begin{aligned} \mathcal{N}_1 - \mathcal{N}_2 &= (\mathcal{O}_{Q_1} - \mathcal{Q}_1)^T \mathcal{G} - (\mathcal{O}_{Q_2} - \mathcal{Q}_2)^T \mathcal{G} = (\mathcal{O}_{Q_1} - \mathcal{O}_{Q_2})^T \mathcal{G} - (\mathcal{Q}_1 - \mathcal{Q}_2)^T \mathcal{G} \\ &= \sum_{i=h_1}^l O_i^1 g_i - \sum_{i=h_2}^l O_i^2 g_i - (Q_1 - Q_2)g_m = \sum_{i=h_1}^{h_2-1} O_i^1 g_i + (O_{h_2}^1 - O_{h_2}^2)g_{h_2} - (Q_1 - Q_2)g_m \\ &> \sum_{i=h_1}^{h_2-1} O_i^1 g_{h_1} + (O_{h_2}^1 - O_{h_2}^2)g_{h_1} - (Q_1 - Q_2)g_m = (Q_1 - Q_2)g_{h_1} - (Q_1 - Q_2)g_m \\ &= (Q_1 - Q_2)(g_{h_1} - g_m) \geq 0. \end{aligned}$$

2. If the order with size Q_1 is unfilled, then there are two possibilities:

(a) The order with size Q_2 is filled and

$$\mathcal{N}_2 \geq 0 > \mathcal{N}_1.$$

(b) The order with size Q_2 is unfilled ($m \geq l$) and

$$\begin{aligned} \mathcal{N}_1 - \mathcal{N}_2 &= (\mathcal{O}_{Q_1} - \mathcal{Q}_1)^T \mathcal{G} - (\mathcal{O}_{Q_2} - \mathcal{Q}_2)^T \mathcal{G} = (\mathcal{O}_{Q_1} - \mathcal{O}_{Q_2})^T \mathcal{G} - (\mathcal{Q}_1 - \mathcal{Q}_2)^T \mathcal{G} \\ &= \sum_{i=h_1}^l O_i^1 g_i - \sum_{i=h_2}^l O_i^2 g_i - (Q_1 - Q_2)g_m = \sum_{i=h_1}^{h_2-1} O_i^1 g_i + (O_{h_2}^1 - O_{h_2}^2)g_{h_2} - (Q_1 - Q_2)g_m \\ &< \sum_{i=h_1}^{h_2-1} O_i^1 g_l + (O_{h_2}^1 - O_{h_2}^2)g_l - (Q_1 - Q_2)g_m = (Q_1 - Q_2)g_l - (Q_1 - Q_2)g_m \\ &= (Q_1 - Q_2)(g_l - g_m) \leq 0. \end{aligned}$$